## NAG Toolbox for MATLAB

# e02aj

# 1 Purpose

e02aj determines the coefficients in the Chebyshev-series representation of the indefinite integral of a polynomial given in Chebyshev-series form.

# 2 Syntax

# 3 Description

e02aj forms the polynomial which is the indefinite integral of a given polynomial. Both the original polynomial and its integral are represented in Chebyshev-series form. If supplied with the coefficients  $a_i$ , for i = 0, 1, ..., n, of a polynomial p(x) of degree n, where

$$p(x) = \frac{1}{2}a_0 + a_1T_1(\bar{x}) + \dots + a_nT_n(\bar{x}),$$

the function returns the coefficients  $a'_i$ , for i = 0, 1, ..., n + 1, of the polynomial q(x) of degree n + 1, where

$$q(x) = \frac{1}{2}a'_0 + a'_1T_1(\bar{x}) + \dots + a'_{n+1}T_{n+1}(\bar{x}),$$

and

$$q(x) = \int p(x)dx.$$

Here  $T_j(\bar{x})$  denotes the Chebyshev polynomial of the first kind of degree j with argument  $\bar{x}$ . It is assumed that the normalized variable  $\bar{x}$  in the interval [-1, +1] was obtained from your original variable x in the interval  $[x_{\min}, x_{\max}]$  by the linear transformation

$$\bar{x} = \frac{2x - (x_{\text{max}} + x_{\text{min}})}{x_{\text{max}} - x_{\text{min}}}$$

and that you require the integral to be with respect to the variable x. If the integral with respect to  $\bar{x}$  is required, set  $x_{\text{max}} = 1$  and  $x_{\text{min}} = -1$ .

Values of the integral can subsequently be computed, from the coefficients obtained, by using e02ak.

The method employed is that of Chebyshev-series (see Chapter 8 of Modern Computing Methods 1961), modified for integrating with respect to x. Initially taking  $a_{n+1} = a_{n+2} = 0$ , the function forms successively

$$a'_{i} = \frac{a_{i-1} - a_{i+1}}{2i} \times \frac{x_{\text{max}} - x_{\text{min}}}{2}, \quad i = n+1, n, \dots, 1.$$

The constant coefficient  $a'_0$  is chosen so that q(x) is equal to a specified value, **qatm1**, at the lower end point of the interval on which it is defined, i.e.,  $\bar{x} = -1$ , which corresponds to  $x = x_{\min}$ .

## 4 References

Modern Computing Methods 1961 Chebyshev-series NPL Notes on Applied Science 16 (2nd Edition) HMSO

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#### 5 Parameters

### 5.1 Compulsory Input Parameters

#### 1: n - int32 scalar

n, the degree of the given polynomial p(x).

Constraint:  $\mathbf{n} \geq 0$ .

#### 2: xmin – double scalar

#### 3: xmax – double scalar

The lower and upper end points respectively of the interval  $[x_{\min}, x_{\max}]$ . The Chebyshev-series representation is in terms of the normalized variable  $\bar{x}$ , where

$$\bar{x} = \frac{2x - (x_{\text{max}} + x_{\text{min}})}{x_{\text{max}} - x_{\text{min}}}.$$

Constraint: xmax > xmin.

### 4: a(la) - double array

The Chebyshev coefficients of the polynomial p(x). Specifically, element  $i \times \mathbf{ia1} + 1$  of **a** must contain the coefficient  $a_i$ , for i = 0, 1, ..., n. Only these n + 1 elements will be accessed.

Unchanged on exit, but see aint, below.

#### 5: ia1 – int32 scalar

The index increment of **a**. Most frequently the Chebyshev coefficients are stored in adjacent elements of **a**, and **ia1** must be set to 1. However, if for example, they are stored in  $\mathbf{a}(1), \mathbf{a}(4), \mathbf{a}(7), \ldots$ , then the value of **ia1** must be 3. See also Section 8.

Constraint:  $ia1 \ge 1$ .

#### 6: qatm1 – double scalar

The value that the integrated polynomial is required to have at the lower end point of its interval of definition, i.e., at  $\bar{x} = -1$  which corresponds to  $x = x_{\min}$ . Thus, **qatm1** is a constant of integration and will normally be set to zero by you.

## 7: iaint1 – int32 scalar

The index increment of **aint**. Most frequently the Chebyshev coefficients are required in adjacent elements of **aint**, and **iaint1** must be set to 1. However, if, for example, they are to be stored in aint(1), aint(4), aint(7),..., then the value of **iaint1** must be 3. See also Section 8.

Constraint:  $iaint1 \ge 1$ .

### 5.2 Optional Input Parameters

None.

### 5.3 Input Parameters Omitted from the MATLAB Interface

np1, la, laint

### 5.4 Output Parameters

#### 1: **aint(laint) – double array**

The Chebyshev coefficients of the integral q(x). (The integration is with respect to the variable x, and the constant coefficient is chosen so that  $q(x_{\min})$  equals **qatm1**). Specifically, element  $i \times \mathbf{iaint1} + 1$  of **aint** contains the coefficient  $a'_i$ , for  $i = 0, 1, \dots, n+1$ . A call of the function may

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have the array name **aint** the same as **a**, provided that note is taken of the order in which elements are overwritten when choosing starting elements and increments **ia1** and **iaint1**: i.e., the coefficients,  $a_0, a_1, \ldots, a_{i-2}$  must be intact after coefficient  $a'_i$  is stored. In particular it is possible to overwrite the  $a_i$  entirely by having **ia1** = **iaint1**, and the actual array for **a** and **aint** identical.

#### 2: ifail – int32 scalar

0 unless the function detects an error (see Section 6).

# 6 Error Indicators and Warnings

Errors or warnings detected by the function:

```
\begin{aligned} & \textbf{ifail} = 1 \\ & & \textbf{On entry, } \textbf{np1} < 1, \\ & \text{or } & \textbf{xmax} \leq \textbf{xmin,} \\ & \text{or } & \textbf{ia1} < 1, \\ & \text{or } & \textbf{la} \leq (\textbf{np1} - 1) \times \textbf{ia1,} \\ & \text{or } & \textbf{iaint1} < 1, \\ & \text{or } & \textbf{laint} \leq \textbf{np1} \times \textbf{iaint1.} \end{aligned}
```

## 7 Accuracy

In general there is a gain in precision in numerical integration, in this case associated with the division by 2i in the formula quoted in Section 3.

## **8** Further Comments

The time taken is approximately proportional to n + 1.

The increments ia1, iaint1 are included as parameters to give a degree of flexibility which, for example, allows a polynomial in two variables to be integrated with respect to either variable without rearranging the coefficients.

## 9 Example

```
n = int32(6);
xmin = -0.5;
xmax = 2.5;
a = [2.53213;
     1.13032;
     0.2715;
     0.04434;
     0.00547;
     0.00054;
     4e-05];
ia1 = int32(1);
qatm1 = 0;
iaint1 = int32(1);
[aint, ifail] = e02aj(n, xmin, xmax, a, ia1, qatm1, iaint1)
aint =
    2.6946
    1.6955
    0.4072
    0.0665
    0.0082
    0.0008
    0.0001
    0.0000
```

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ifail = 0

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